

ME 4452 Control of Dynamic Systems (Elective)

- Catalog Description:** ME 4452 Control of Dynamic Systems (3-0-3)
Prerequisites: ME 3017 System Dynamics
Modeling and simulation of dynamic systems in frequency and time domains. Feedback control analysis and design methods including root-locus, frequency response, and pole-placement. Introduction to digital control systems.
- Textbook:** Norman S. Nise, *Control Systems Engineering*, 6th Edition, Wiley, 2010.
- References:** Katsuhiko Ogata, *Modern Control Engineering*, 5th Edition, Prentice Hall, 2009.

Topics Covered:

1. Modeling in the Laplace domain
2. Modeling in the time domain
3. Time response analysis and specifications
4. Stability analysis
5. Steady-state errors
6. Root-locus control design
7. Frequency response control design
8. State-space control design
9. Introduction to digital control systems
10. Control system applications and case studies

Course Outcomes:

Outcome 1: To teach students to perform a mathematical analysis of engineering dynamic systems in the time and frequency domains.

- 1.1 Students will demonstrate an understanding of various mathematical models, such as differential equation and transfer function models.
- 1.2 Students will demonstrate the ability to formulate state-space models of dynamic systems.
- 1.3 Students will demonstrate the ability to linearize the dynamic model of nonlinear systems.

Outcome 2: To develop students' understanding of stability, transient, and steady-state behavior of linear dynamic systems.

- 2.1 Students will demonstrate the ability to formulate the time response of a linear system based on its transfer function or state-space model.
- 2.2 Students will demonstrate the ability to derive the frequency response of a linear system and to construct its Bode diagrams.
- 2.3 Students will demonstrate the ability to identify a dynamic system from its time or frequency response.
- 2.4 Students will demonstrate how to evaluate the stability of dynamic systems both in the time and frequency domains.
- 2.5 Students will demonstrate an understanding of the transient and steady-state response specifications for dynamic systems.

Outcome 3: To develop students' skills in analyzing and designing feedback controllers in the time and frequency domains.

- 3.1 Students will demonstrate the ability to reduce block diagrams of multiple subsystems.
- 3.2 Students will demonstrate that they can analyze and design controllers using the root-locus technique.
- 3.3 Students will demonstrate the ability to design control compensation using frequency domain techniques.
- 3.4 Students will demonstrate an ability to design controllers in the time-domain using state-space methods.
- 3.5 Students will demonstrate when and how to apply various control design techniques to real-world engineering systems.
- 3.6 Students will demonstrate the ability to evaluate the performance of control systems by simulation.

Correlation between Course Outcomes and Student Outcomes:

ME 4452											
Course Outcomes	Mechanical Engineering Student Outcomes										
	a	b	c	d	e	f	g	h	i	j	k
Course Outcome 1.1	X										
Course Outcome 1.2	X										
Course Outcome 1.3	X										
Course Outcome 2.1	X				X						
Course Outcome 2.2	X				X						
Course Outcome 2.3	X				X						
Course Outcome 2.4	X				X						
Course Outcome 2.5	X				X						
Course Outcome 3.1					X						
Course Outcome 3.2					X						
Course Outcome 3.3					X						
Course Outcome 3.4					X						
Course Outcome 3.5										X	X
Course Outcome 3.6										X	X

GWW School of Mechanical Engineering Student Outcomes:

- (a) an ability to apply knowledge of mathematics, science and engineering
- (b) an ability to design and conduct experiments, as well as to analyze and interpret data
- (c) an ability to design a system, component, or process to meet desired needs within realistic constraints such as economic, environmental, social, political, ethical, health and safety, manufacturability, and sustainability
- (d) an ability to function on multidisciplinary teams
- (e) an ability to identify, formulate, and solve engineering problems
- (f) an understanding of professional and ethical responsibility
- (g) an ability to communicate effectively

- (h) the broad education necessary to understand the impact of engineering solutions in a global, economic, environmental, and societal context
- (i) a recognition of the need for, and an ability to engage in life-long learning
- (j) a knowledge of contemporary issues
- (k) an ability to use the techniques, skills, and modern engineering tools necessary for engineering practice

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